Matlab Control System Toolbox Download Free 2012

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>> Ts=1;
>> S=mld('bm99', Ts);
>> Q.y=1;
>> Q.norm=2;
>> limits.wmin=-1;
>> limits.wmax=1;
>> C=hybcon(S,Q,N,limits,refs)
Hybrid controller based on MLD model S dom99.hys> [2-norm]
  2 state measurement(s)
  1 output reference(s)
  0 input reference(s)
  O state reference(s)
  O reference(s) on auxiliary continuous z-variables
  8 optimization variable(s) (6 continuous, 2 binary)
 32 mixed-integer linear inequalities
sempling time = 1, MIQP solver = 'miqp'
20
```

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